

## Course overview.

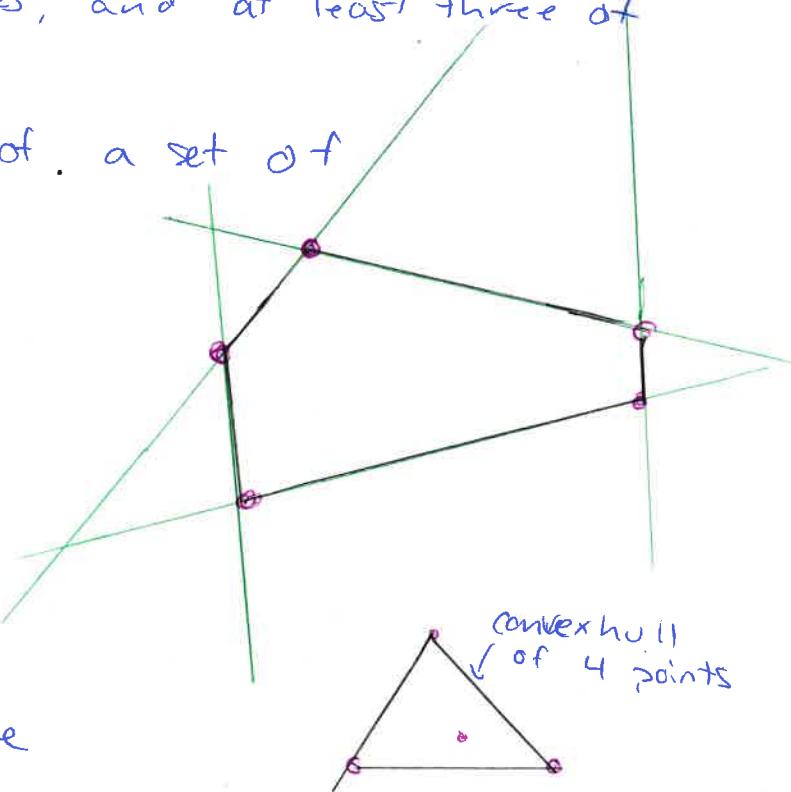
- Plane geometry : convex polygons.

What is a convex polygon in  $\mathbb{R}^2$ ?

- The convex hull of a set of points (at least 3)
- A shape bounded by straight lines, that has as many vertices as edges, and at least three of them. + It is convex.
- It is a bounded region of a set of lines.

Possible counting questions:

- How many points are really needed to define it?
- What is its area?
- How many triangulations are there?
- How many bounded regions are there, for a set of lines?
- Higher dimensions : convex polytopes.
  - Given a set of properties, can a polytope with all of them exist ?

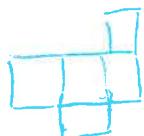


The geometry of geometries: matroids.

- Generalizes the notion of independence:
  - Linear independence of vectors
  - Acyclic graphs
- Gives new perspectives on hyperplane arrangements and simplicial complexes.
- We understand matroids from their invariants, and graph theory shows up in surprising places.

Polygons, again

- Given a convex polygon (of a fixed size), is it possible to tile the plane with infinitely many copies of it?
- Can that happen in more than one way?
- Dropping the convexity requirement, can a polyomino tile the plane?

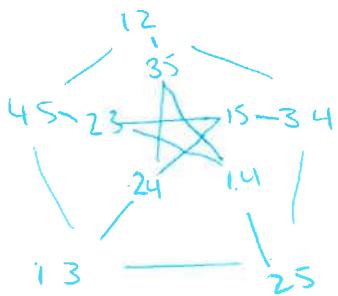


- allowing only translations?
- allowing rotations and translations?

Topological methods

A Kneser graph  $KG_{n,k}$  has  $\binom{n}{k}$  vertices, and two vertices (corresponding to subsets of size  $k$  of  $[n]$ ) share an edge if they are disjoint.

## Example



The Petersen graph is a Kneser Graph ( $KG_{5,2}$ ) with chromatic number 3.

Theorem (Lovász 1978, conjectured by Kneser 1955)

The chromatic number of  $KG_{n,k}$  is  $n-2k+2$ .

Theorem (Borsuk-Ulam)

Every continuous function from an  $n$ -sphere to an  $n$ -Euclidean space maps some pair of antipodal points to the same point.

Surprising fact: Borsuk-Ulam's Theorem is the main tool in Lovász's theorem!!!

The proof of the Kneser graph conjecture by Lovász is referred to as the beginning of topological combinatorics.