

Matroids are structures that generalize vector spaces, in the way that they are (finite) sets with a notion of independence.

Definition

A (finite) matroid is a pair $(S, \mathcal{I})$, where S is a finite set and $\mathcal{I}$ is a collection of subsets of S , satisfying:

- (i) $\mathcal{I}$ is nonempty, and if $J \in \mathcal{I}$ and $I \subseteq J$, then $I \in \mathcal{I}$
(order ideal property, or simplicial complex property)
- (ii) If $I, J \in \mathcal{I}$ and $|I| < |J|$, there exists $x \in J \setminus I$ such that $I \cup \{x\} \in \mathcal{I}$.

The elements of $\mathcal{I}$ are the independent sets.

Examples

- Vector spaces

S = a set of vectors (might not all be linearly independent).

$\mathcal{I}$ = subsets of S containing linearly independent vectors

- Hyperplane arrangements

Taking S as the vectors normal to the hyperplanes, and their span is a vector space.

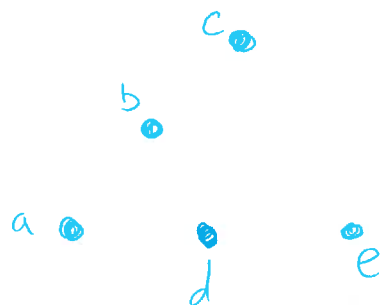
Moreover, if the arrangement is central, the poset we get by inclusion is isomorphic to the intersection lattice.

* It might not be obvious

Example

(2)

Let a, b, c, d, e be points in $\mathbb{R}^2$ and consider $\{x, y\}$ to be the minimal affine subspace containing x and y (if the set has two elements, it will always be a line, but $\{x, y, z\}$ could either be a line or a plane).



$$S = \{a, b, c, d, e\}$$

$\mathcal{J} \subseteq \mathcal{P}(S)$ if the minimal affine subspace spanned by J has dimension $\neq J-1$ ($\emptyset \in \mathcal{J}$)

The poset of minimal affine subspaces of $\mathbb{R}^2$ containing points in S : (order is inclusion).

$\square$ are the independent sets

for example, $abc \notin \mathcal{J}$

because removing one point among

a, b, c returns either ab, bc or ac , and none of them are in S .

Note: All subsets of S are part of the matroid, even if they do not appear in the poset above (which is called the "poset of flats").

Characterization of independence (for this poset):

$A \subseteq \{a, b, c, d, e\}$ is independent iff its rank in the poset is the cardinality of A .

Example

$\mathcal{B}_3$ as a hyperplane arrangement

Definitions

- A basis is a maximal independent set.
- A circuit is a minimal dependent set.
- The rank of $A \subseteq S$ is $\max\{|X| : X \subseteq A, X \in \mathcal{I}\}$.

Example

- For vector spaces, a basis is the usual thing we know.
- For a vector space, the rank is the dimension of the space it spans.

Example

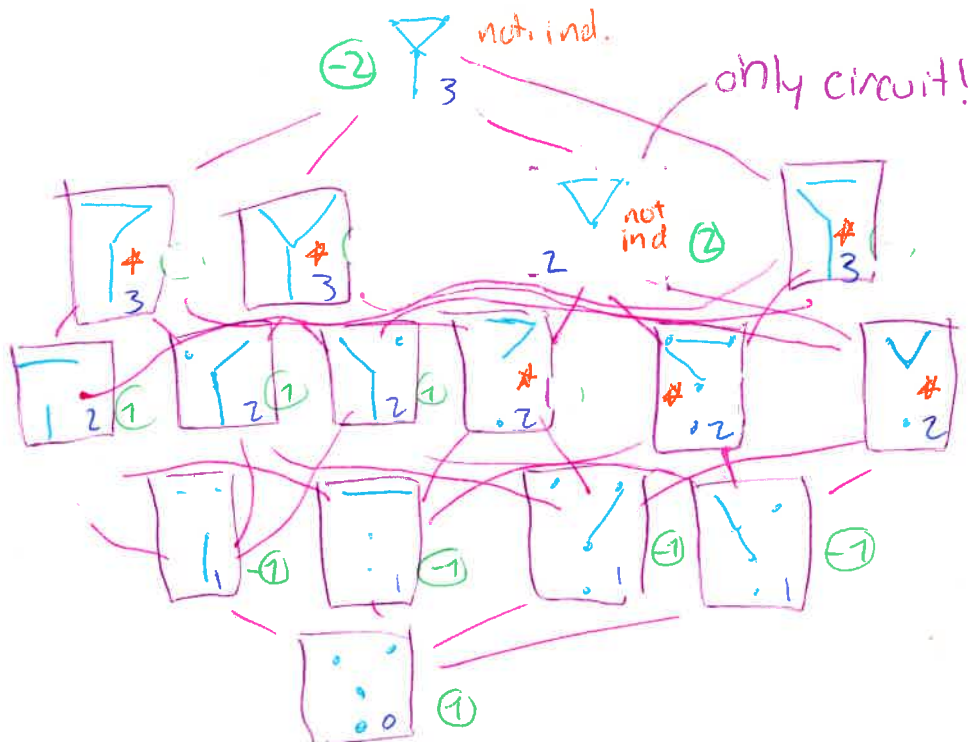
Matroids from a graph: $G = (V, E) =$ 

E is the set of elements. A subset of edges is independent if they do not contain a cycle (or, if they are a forest).

$$F = \{B \subseteq E \mid B \text{ is a forest}\}$$

(E, F) is a matroid.

F
rank
 $\mathcal{I}$ (for a subset)
* not closed



Definition

(4)

Fix a total ordering on S .

A broken circuit is a subset of S of the form $\hat{C} = C \setminus \{\min_{\prec}(C)\}$, where C is a circuit.

Example

For the graph on page 3, fix the following order



There is only one circuit in $\mathbb{Z}^E$: $C = \nabla$, and its minimal element is $\overline{1}$. Thus, the only broken circuit of (E, F) is ∇ .

Example

Fix $a < b < c < d < e$. $M^{(S, \prec)}$ (on page 2) contains circuits abc , ade and $bode$. The 3 broken circuits of M are bc , de and cde .

The broken circuit complex $BC(M)$ is an abstract simplicial complex (i.e. $T \in BC(M)$ and $U \subseteq T \Rightarrow U \in BC(M)$) defined by:

$$BC(M) = \{T \subseteq S : T \text{ contains no broken circuit}\}$$

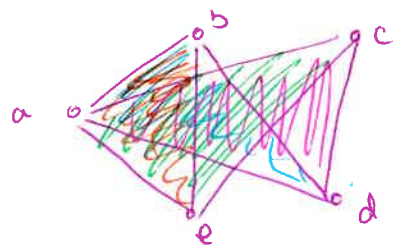
Example

The broken circuit complex of (E, F) is all the subsets of E that do not contain ∇ . As a simplicial complex, it is spanned by $\overline{1}$ and $\overline{2}$ (i.e. all elements of BC are included in these two) and we get the following simplicial complex.

Example

For the affine spaces on page 2, the broken circuits are bc, de and cde . And all elements of M that do not contain bc, de or cde are included in either abd, abe, acd or ace .

Thus, the simplicial complex $BC(M)$ is



Dimension faces.

Definition

The closure of a subset A of S for a matroid $(S, \mathcal{I})$ is

$$\text{clos}(A) = \{x \in S \mid \text{rank}(A \cup \{x\}) = \text{rank}(A)\}.$$

A subset A is closed if $\text{clos}(A) = A$.

Alternatively, A is closed if it is maximal among elements of the same rank.
e.g. in $(E, \mathcal{I})$, $\mathcal{I}$ is not closed, because ∇ has same rank.

Definition/Theorem

The characteristic polynomial of a matroid $M = (S, \mathcal{I})$ admits the

equivalent definitions

$$\chi_M(t) = \sum_{x \in \text{clos}(M)} \mu(\hat{0}, x) t^{\text{rank}(M) - \text{rank}(x)}$$

max. rank for element in M .

where clos is the induced subposet of closed subsets of S , and the Möbius function is computed on that poset.

$$\chi_M(t) = \sum_{i=0}^{\text{rank}(M)} (-1)^i f_{i-1}(BC(M)) t^{\text{rank}(M)-i},$$

where f_{i-1} is the number of faces of dimension i in $BC(M)$.

Examples

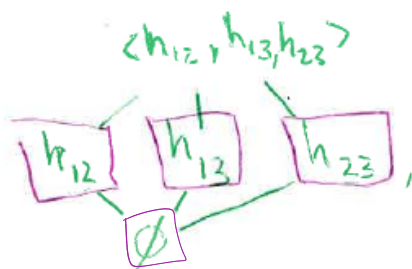
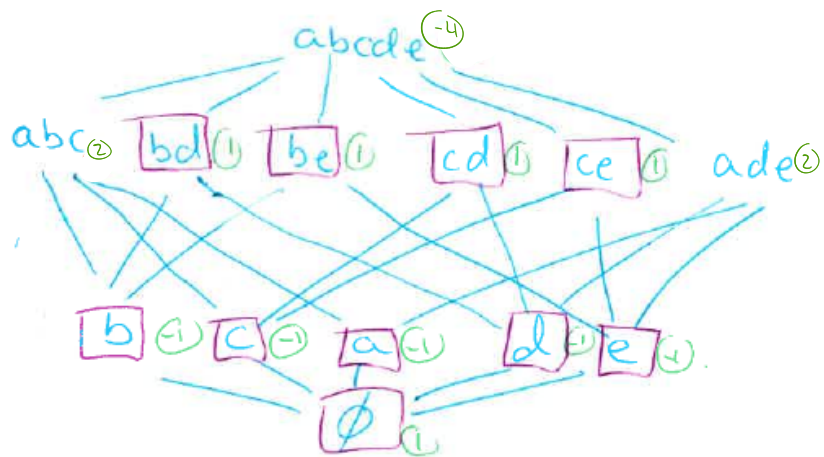
We can compute in two ways the characteristic polynomials of $M = (S, \mathcal{I})$ and $(E, \mathcal{F})$.

$$\chi_M(t) = t^3 - 5t^2 + 8t - 4 \quad \text{and} \quad \chi_{(E, \mathcal{F})}(t) = t^3 - 4t^2 + 5t - 2.$$

References:

Richard P. STANLEY. An Introduction to Hyperplane Arrangements. §3, 4.

Page 2



where h_{ij} is
normal to H_{ij} .

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Dimension	# faces
-1	1
0	4
1	5
2	2

Page 5

Dimension	# faces
-1	1
0	5
1	8
2	4